

Training Language Models to Reason - II

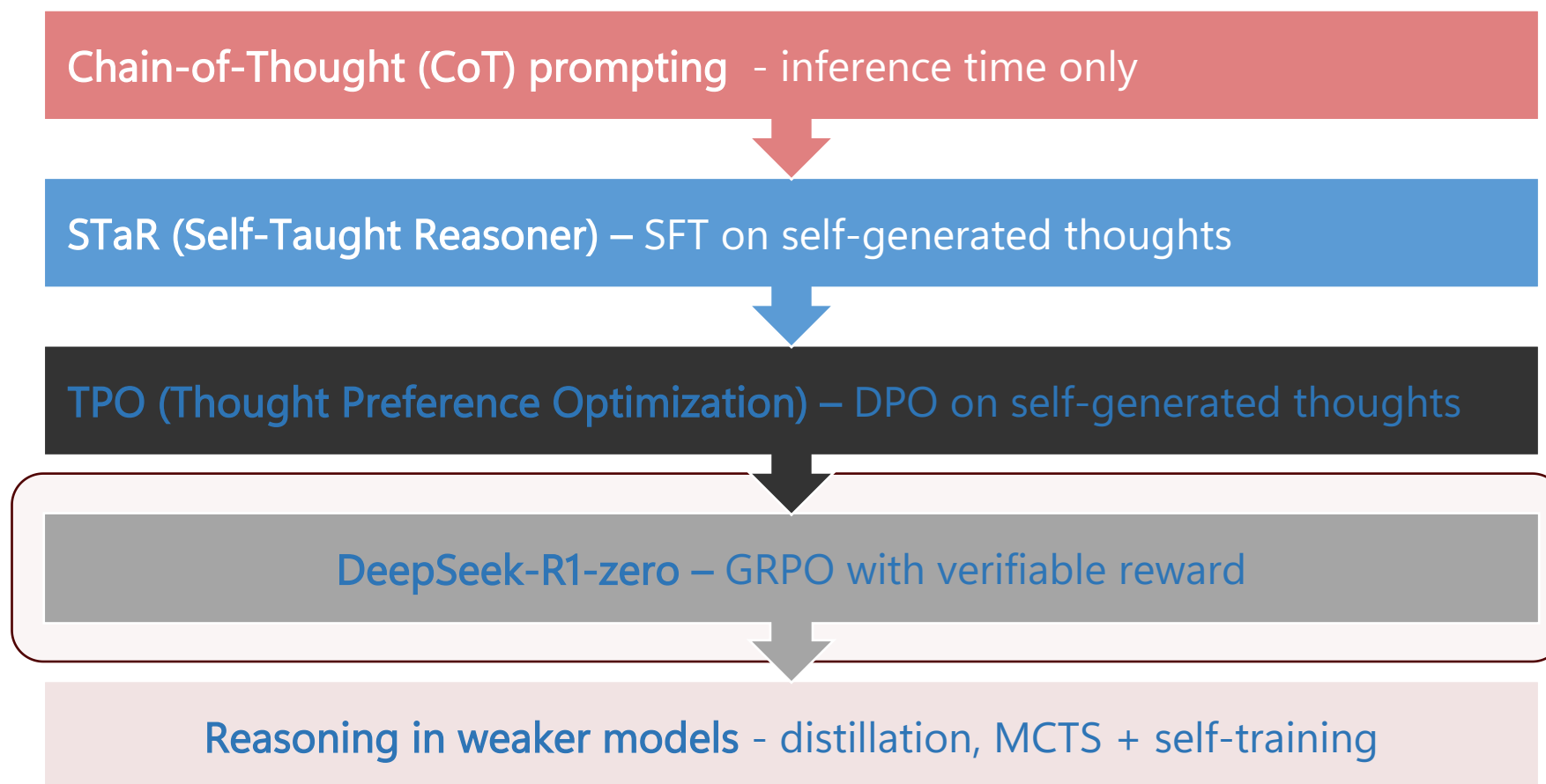
Advances in Large Language Models

ELL8299 · AIL861



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Research

The Flow

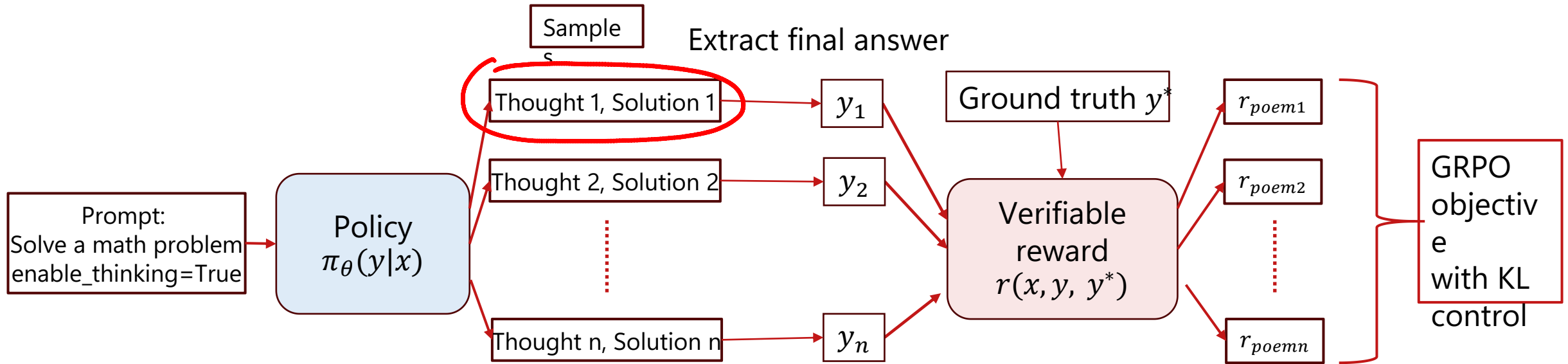


Verifiable rewards

- Rewards that can be computed objectively and reproducibly from a ground truth.
- Examples of Verifiable Reward Functions
 - **Math:** Exact numerical answer match
 - **Code:** Passes all test cases
 - **QA:** String match or F1-score over entities
 - **Formal logic tasks:** Correct proof sequence
 - **Chemistry:** Exact Match in Reaction Prediction
 - **Biology:** RMSD for Protein structure prediction
- Does not depend on noisy human or AI preferences.
- Responsible for the latest revolution in reasoning in AI
(Deepseek-R1, OpenAI o1, Kimi K1.5 and Kimi K2, Qwen3)



RL with verifiable rewards



$$r_1 \log \pi_{\theta}(y_1|x) + \dots + r_n \log \pi_{\theta}(y_n|x)$$



The GRPO objective – a quick recap

$$L^{GRPO}(\theta) = E[\min(r_t(\theta)\hat{A}(y_i), \text{clip}(r_t(\theta), 1 - \epsilon, 1 + \epsilon)\hat{A}(y_i))]$$

GRPO Sampling - $\pi_{\theta_{old}}$.

$$r_t(\theta) = \frac{\pi_{\theta}(y|x)}{\pi_{\theta_{old}}(y|x)}$$



The GRPO objective – a quick recap

$$L^{GRPO}(\theta) = E[\min(r_t(\theta)\hat{A}(y_i), \text{clip}(r_t(\theta), 1 - \epsilon, 1 + \epsilon)\hat{A}(y_i))]$$

- $r_t(\theta)$ is the probability ratio $\frac{\pi_{\theta}(a_t|s_t)}{\pi_{\theta_{old}}(a_t|s_t)}$
 - a_t is the t^{th} token of the generated output
 - s_t is the tokens before a_t
 - $\pi_{\theta_{old}}$ is the distribution from which y_i was sampled.

- Key trick of GRPO - Advantage is relative

$$A(y_i) = \frac{r(y_i) - \text{mean}(r(y_1), \dots, r(y_K))}{\text{stddev}(r(y_1), \dots, r(y_K))}$$



Deepseek-R1-zero → there is no SFT

- Uses a strong base model – Deepseek-V3-base
 - Extensive Math and Code data – sources not stated
- Prompt Template

A conversation between User and Assistant. The user asks a question, and the Assistant solves it.

The assistant first thinks about the reasoning process in the mind and then provides the user with the answer. The reasoning process and answer are enclosed within `<think>` `</think>` and `<answer>` `</answer>` tags, respectively, i.e., `<think>` reasoning process here `</think>` `<answer>` answer here `</answer>`. User: **prompt**. Assistant:

- Uses GRPO with RLVR for Maths & Coding problems



Reward Modelling

- Accuracy reward for Math
 - Instruct the model to put the final output in a specific format
 - Extract the output from the generated response
 - Verify against the ground truth answer.
- Accuracy reward for Code
 - Run unit tests on the generated code
- Format reward
 - The format should look like
< think > Thought process </think > < response > Response </response >

+1, -1



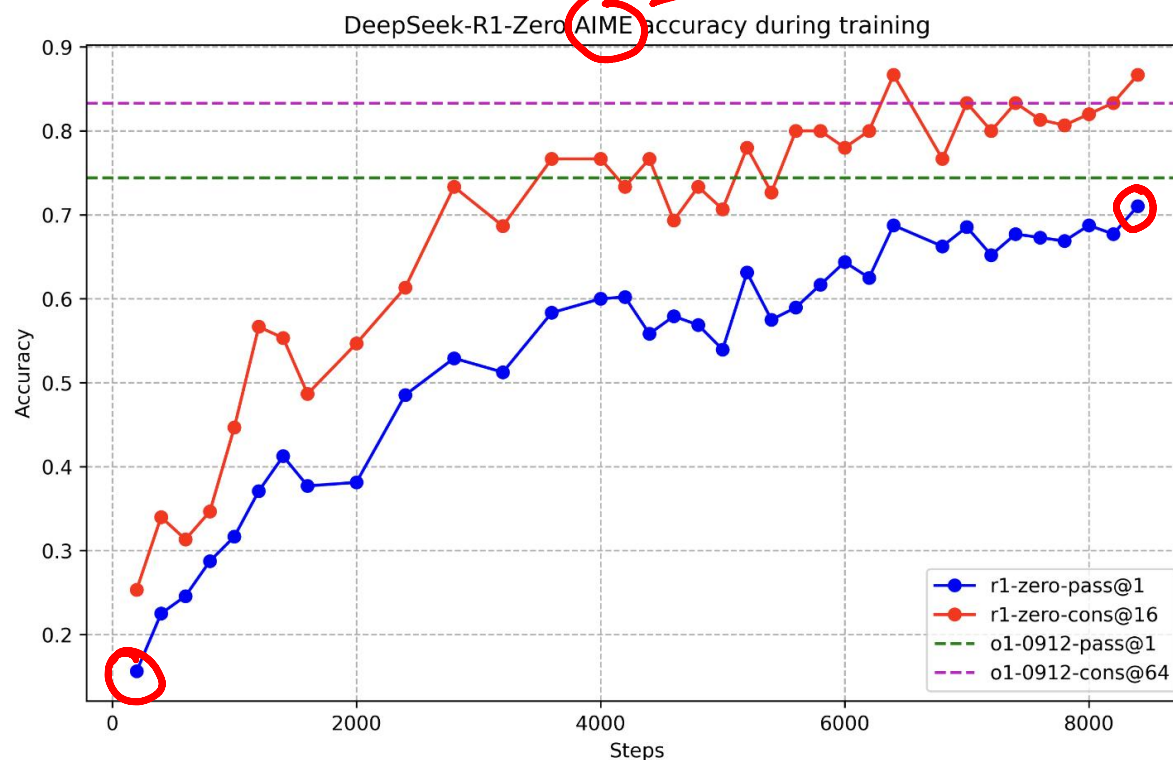
RL training - performance

- GRPO on top of math and code data

Olympiad

Math problems
1983 - 2023

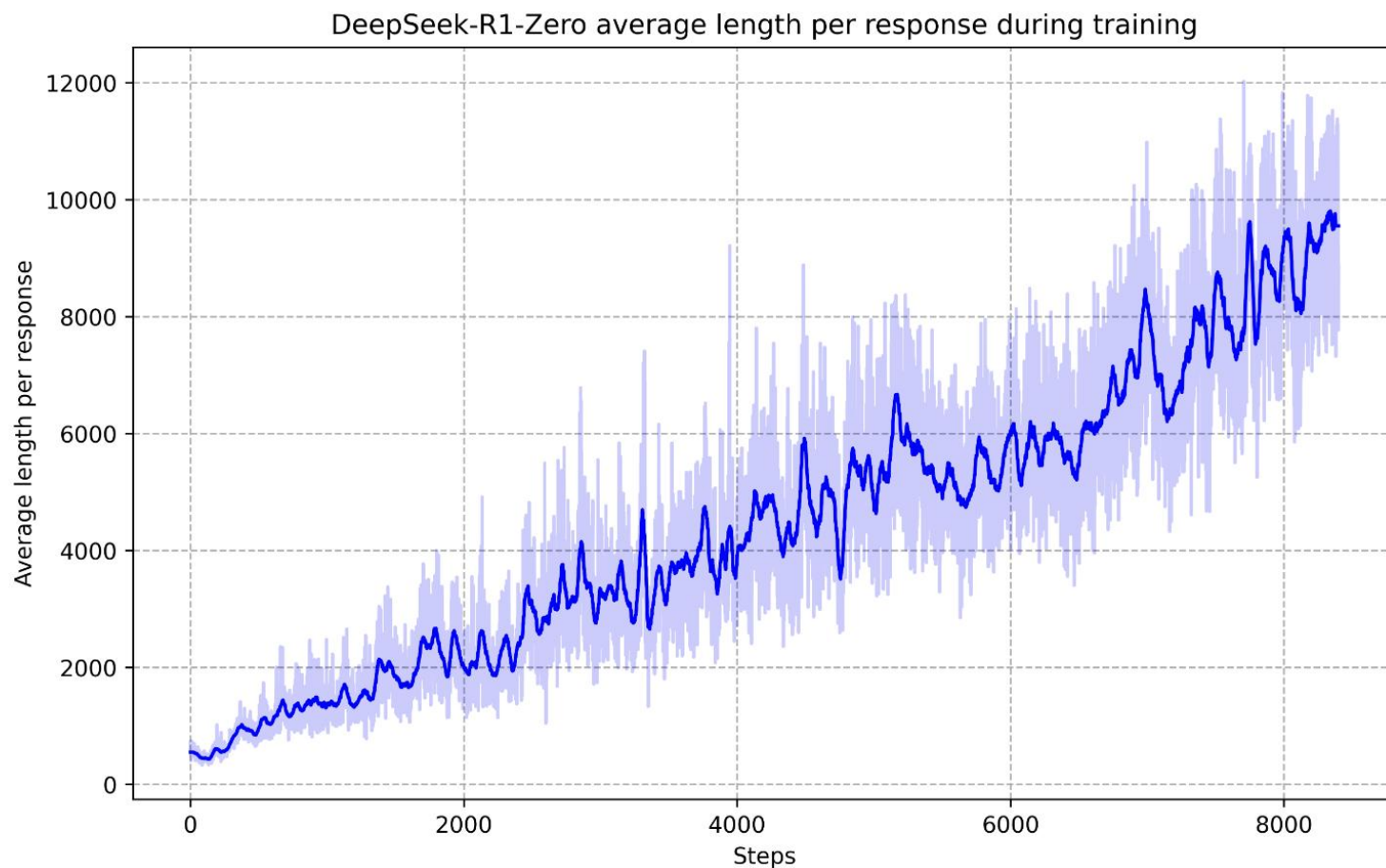
2024 & 2025
Evaluation



AIME accuracy of Deepseek-R1-Zero increases with the number of RL steps



RL training – length of responses



Length of responses increases with the number of RL steps



Why do the lengths increase?

- Emergence of new reasoning patterns – the aha moment

✓ Verifications
"Let me check
my answer ..."

Subgoal Setting
"Let's try to get to a
multiple of 10"

??

✓ Backtracking
"Let's try a different
approach, what if we ..."

Backward Chaining
"Working backwards, 24
is 8 times 3"

??

Gandhi et al. Cognitive Behaviors that Enable Self-Improving Reasoners. arXiv 2025



An example

Problem:

James writes a 3-page letter to 2 different friends twice a week. How many pages does he write a year?

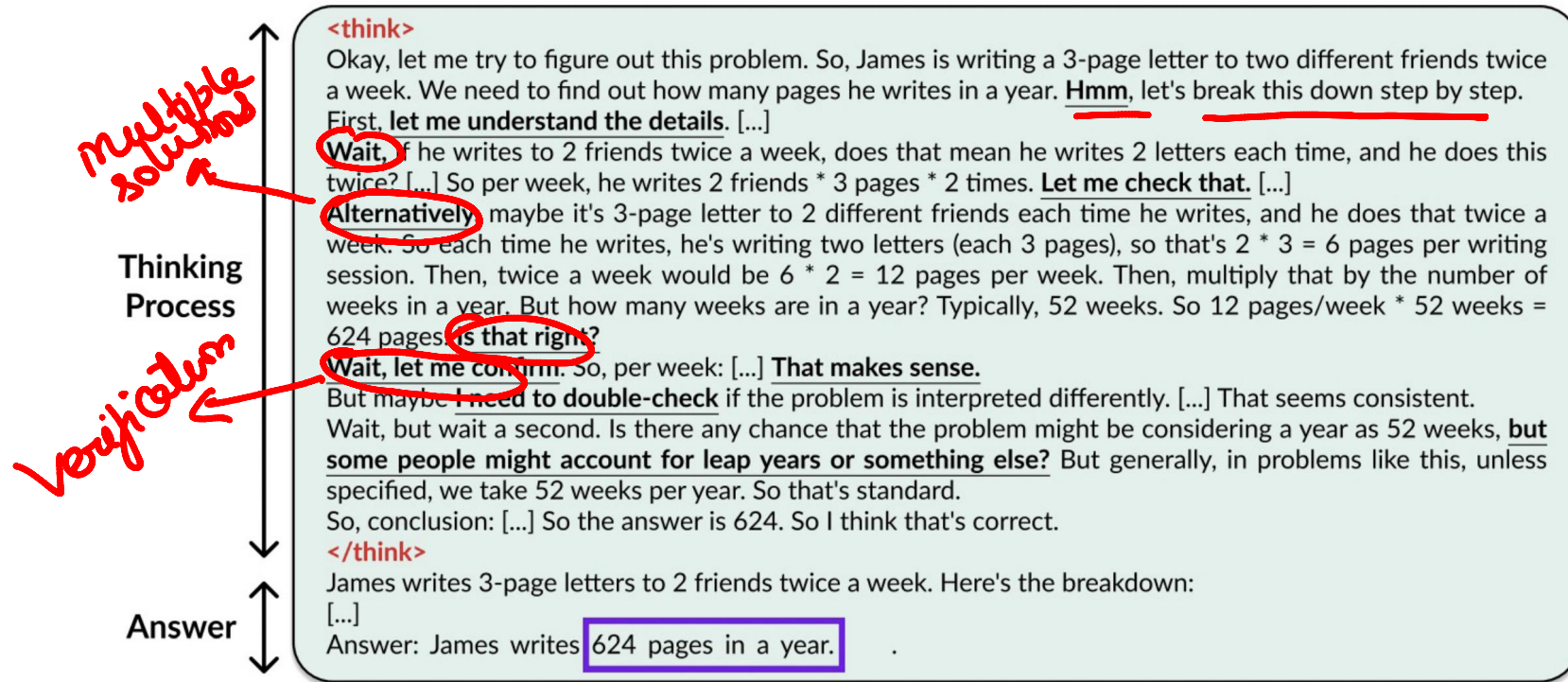
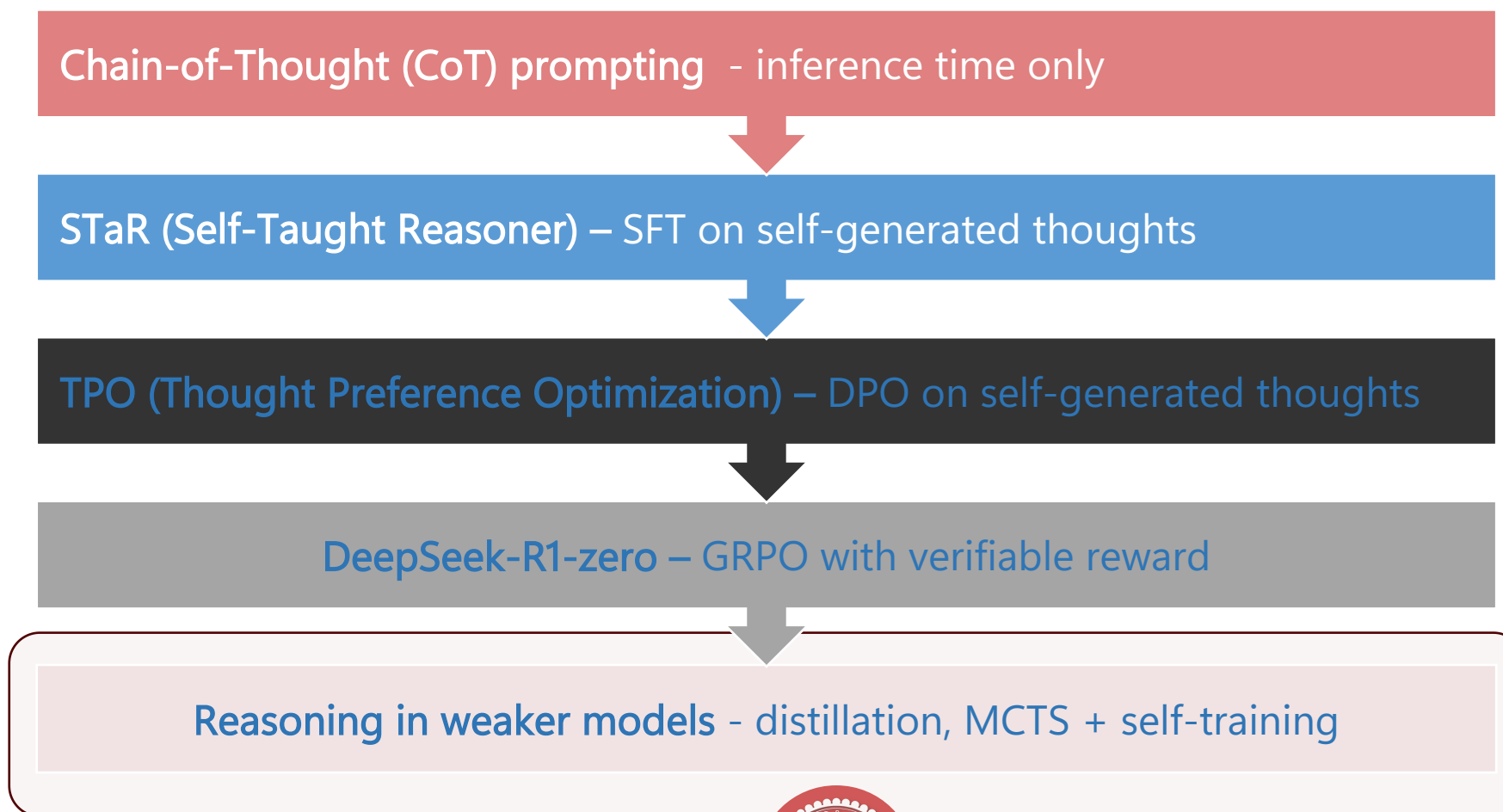


Figure from: Marjanović et al. DeepSeek-R1 Thoughtlogy. arXiv 2025.



The Flow



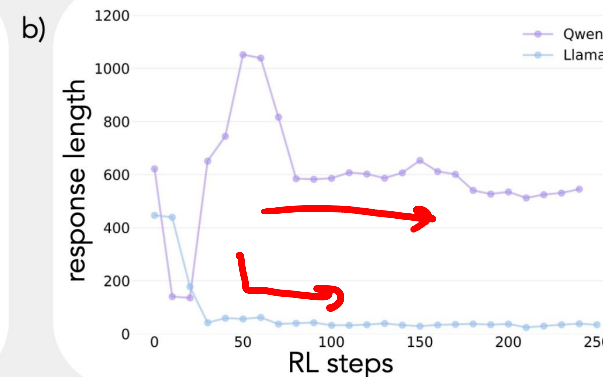
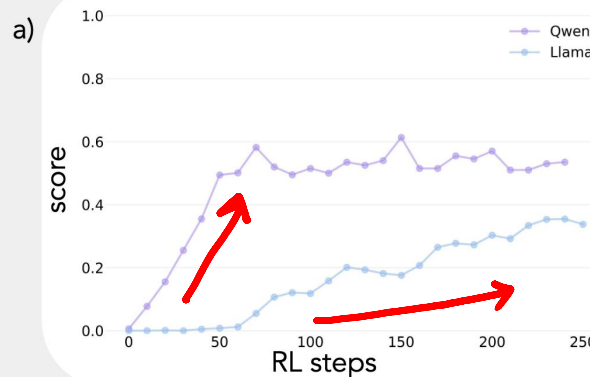
Will this work on all models?

- Short answer, no
- The model must have seen such patterns during its pretraining.
- Countdown game — a mathematical puzzle where players must combine a set of input numbers using the four basic arithmetic operations (+, −, ×, ÷) to reach a target number.

A tale of two models: Qwen 2.5 3B and Llama 3.2 3B

Let's start with the sum of the largest two numbers and then subtract the smallest two: $84 + 83 - 34 - 72$. This gives us $167 - 76$ which equals 91. That's not 39. Let's try another combination: $84 + 83 - 72 - 34$. This gives us $167 - 106$ which equals 61. That's still not 39. Let's try $84 + 72 - 83 - 34$. This gives us $156 - 117$ which equals 39. This is the correct equation.

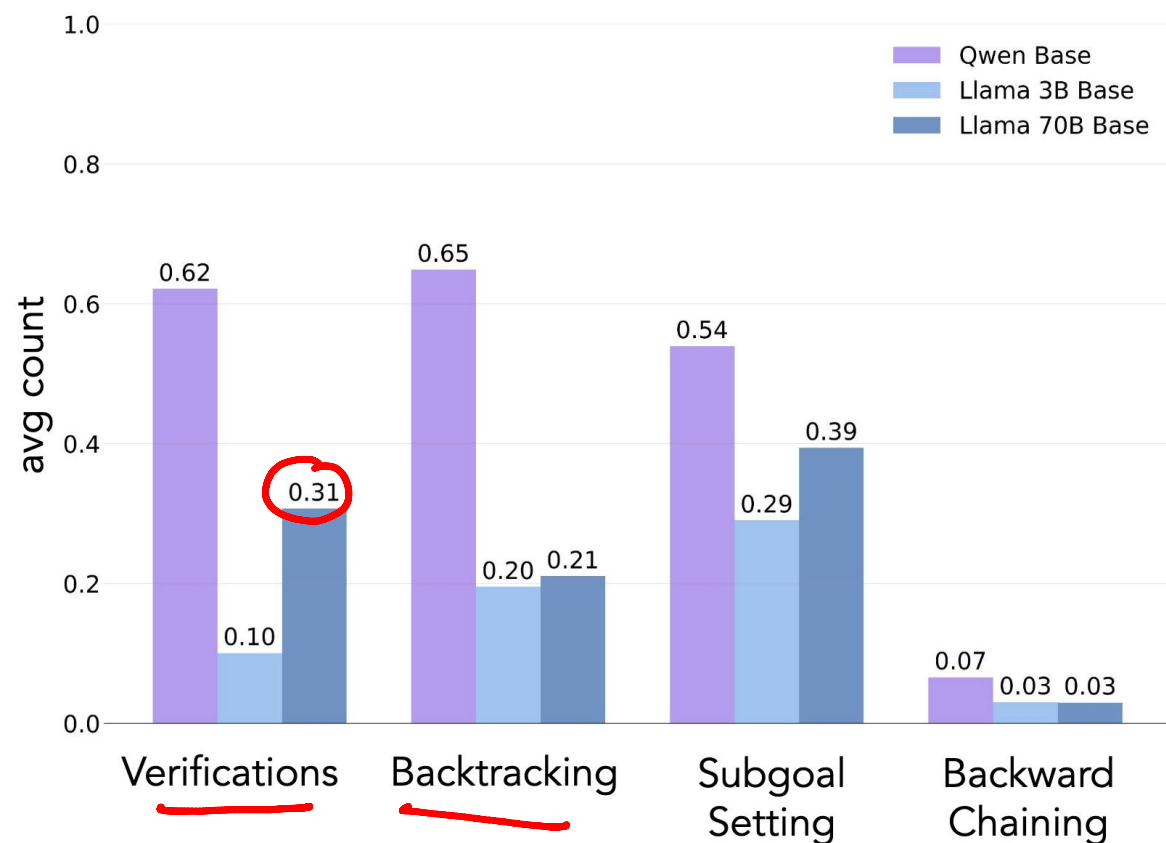
84 is the difference between 108 and 34.
<answer> $(84 - 34) / 108$ </answer>



Gandhi et al. Cognitive Behaviors that Enable Self-Improving Reasoners. arXiv 2025



The role of initial behavior



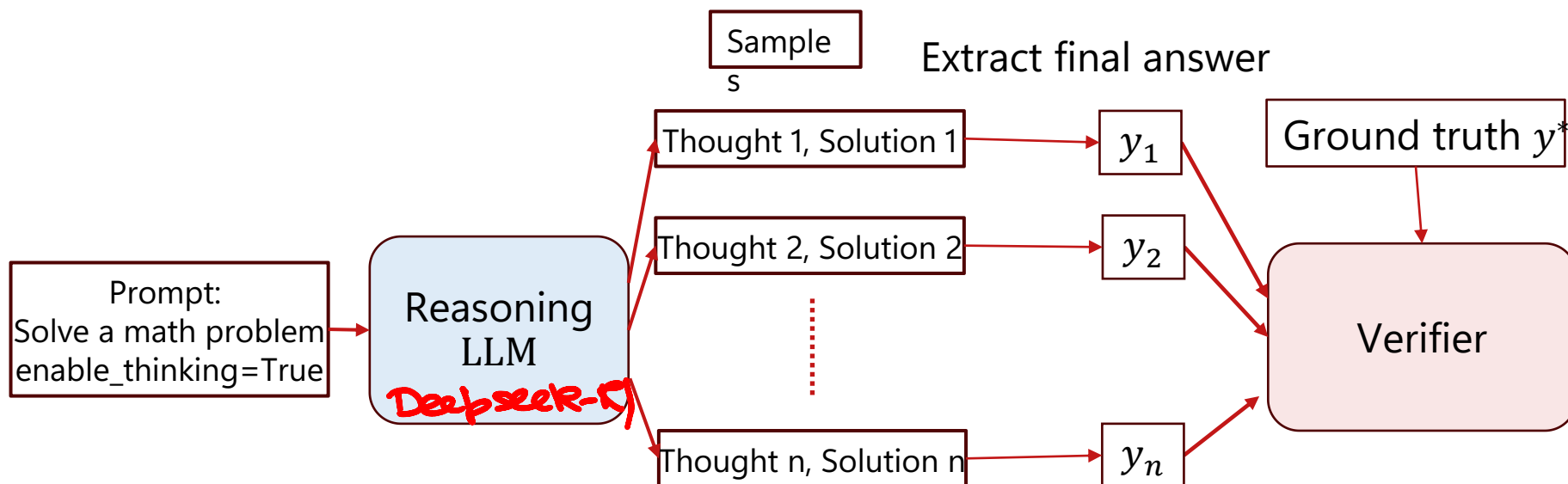
- Qwen-2.5-3B models already exhibit all the 4 behaviors at a much higher rate than Llama-70B.
- The initial policy must show the cognitive behavior for RL to exploit it.

Gandhi et al. Cognitive Behaviors that Enable Self-Improving Reasoners. arXiv 2025



Inducing reasoning patterns in weaker models

For verifiable problems



- Keep verified (prompt, thought, solution) triplets
- Perform SFT on these triplets



Distillation vs RL for weak models

- Always prefer distillation from a powerful reasoning model.
- RL on weak models may never be able to find trajectories that have already been discovered by more powerful models

Model	AIME 2024		MATH-500	GPQA Diamond	LiveCodeBench
	pass@1	cons@64	pass@1	pass@1	pass@1
QwQ-32B-Preview	50.0	60.0	90.6	54.5	41.9
DeepSeek-R1-Zero-Qwen-32B	47.0	60.0	91.6	55.0	40.2
DeepSeek-R1-Distill-Qwen-32B	72.6	83.3	94.3	62.1	57.2



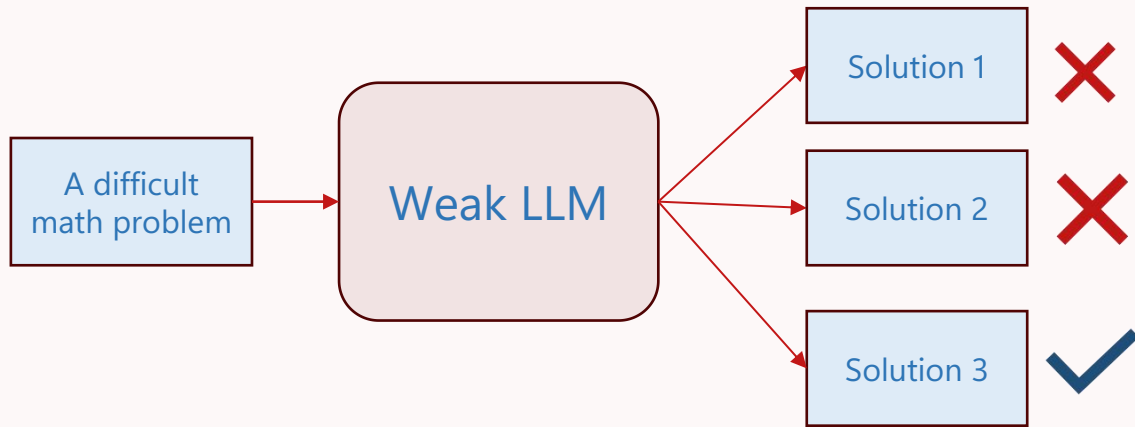
What if no teacher is available?

- Find challenging math problems
- Artificially create solutions with backtracking, verification, restarts, etc.
- SFT the model with these solutions to induce such behaviors in the model
- Then, do RL on hard problems – **GRPO + RLVR**

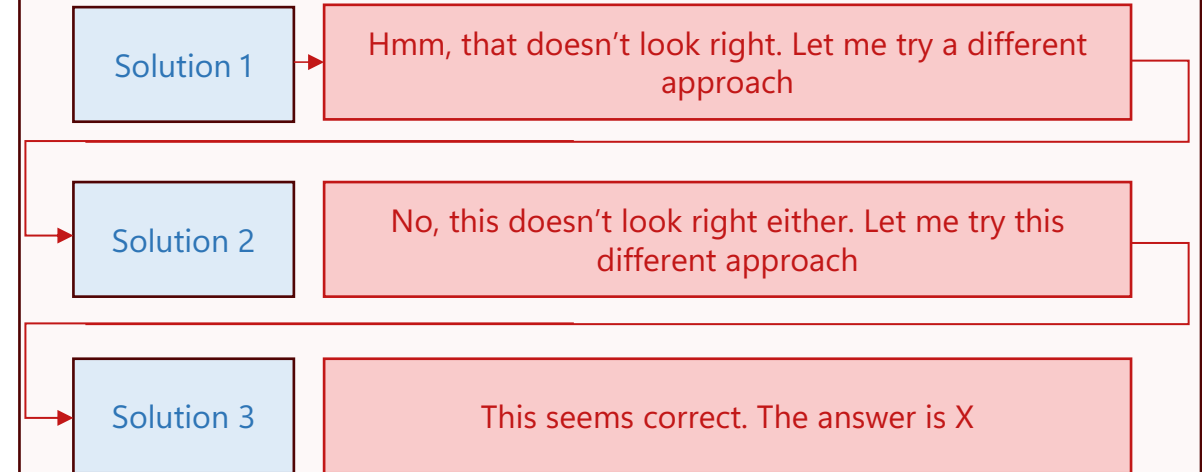


Teaching restarts

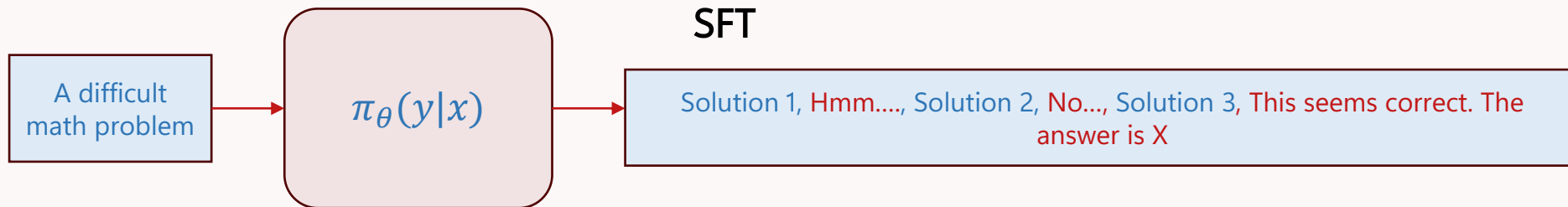
Sampling



Linearization

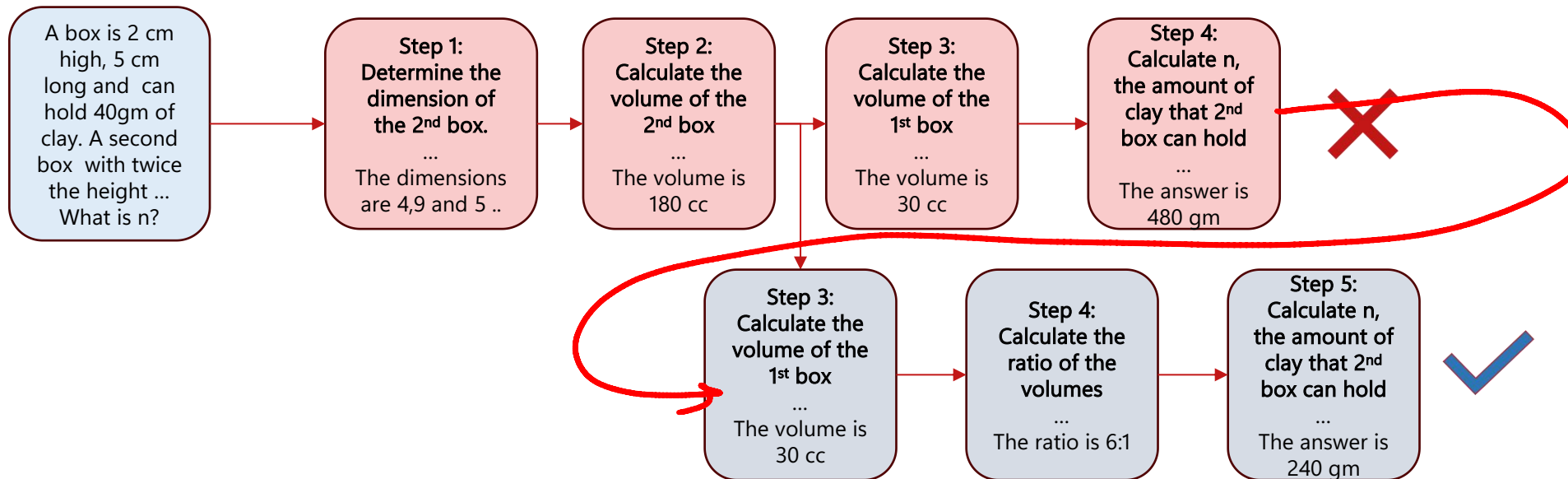


SFT

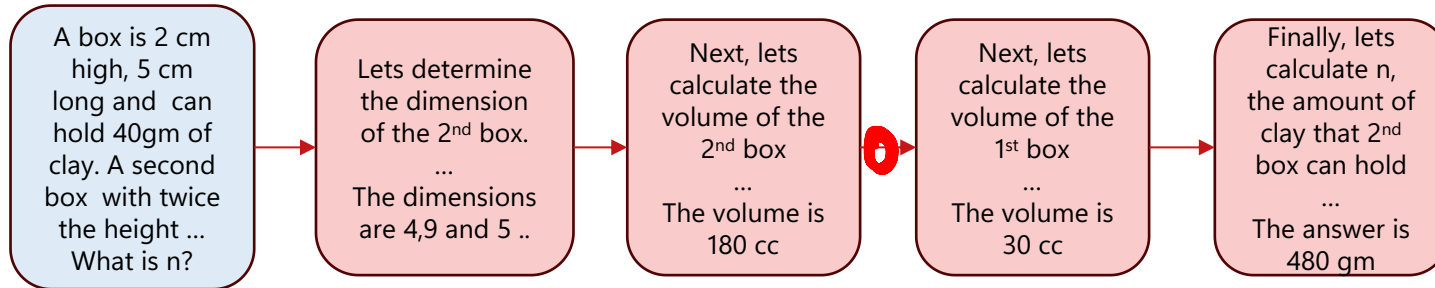


What about backtracking?

this was a mistake



Rewriting steps

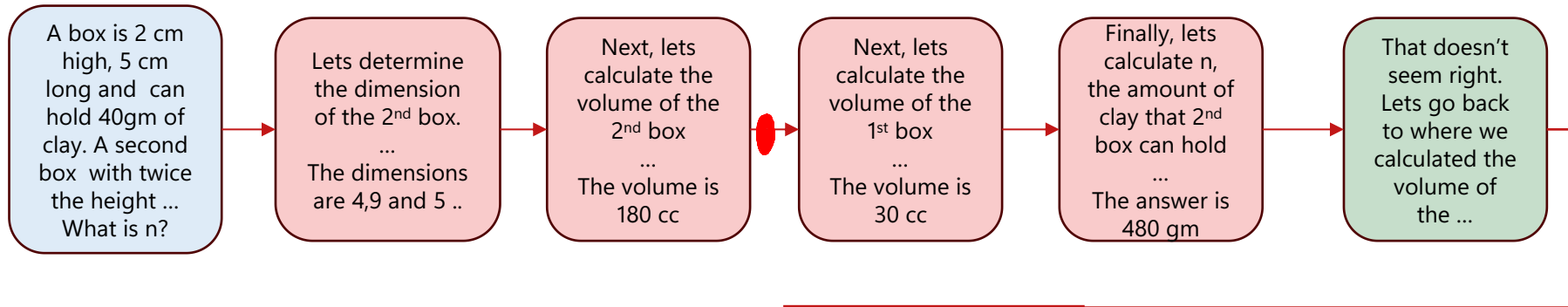


Prompt to rewrite each step

Given a partially thought-out solution to a math problem so far and the current step for solving the problem, your job is to rewrite the *current step* into a thought that smoothly continues the previous thoughts. This rewritten thought should only address the contents of the current step itself, nothing more or less.

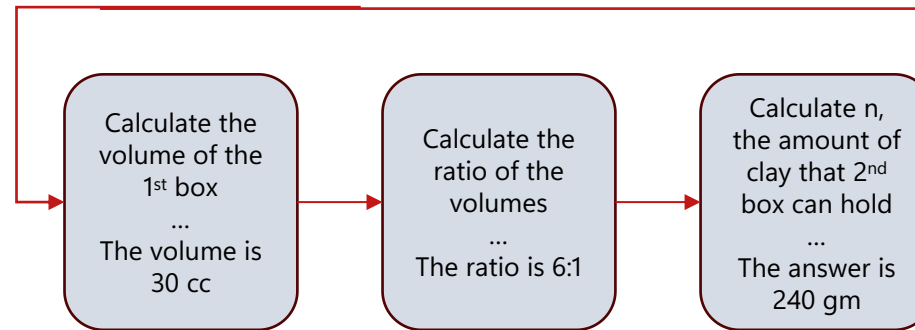
Each step is rewritten by the LLM based on the previous steps

Linearization of backtracking



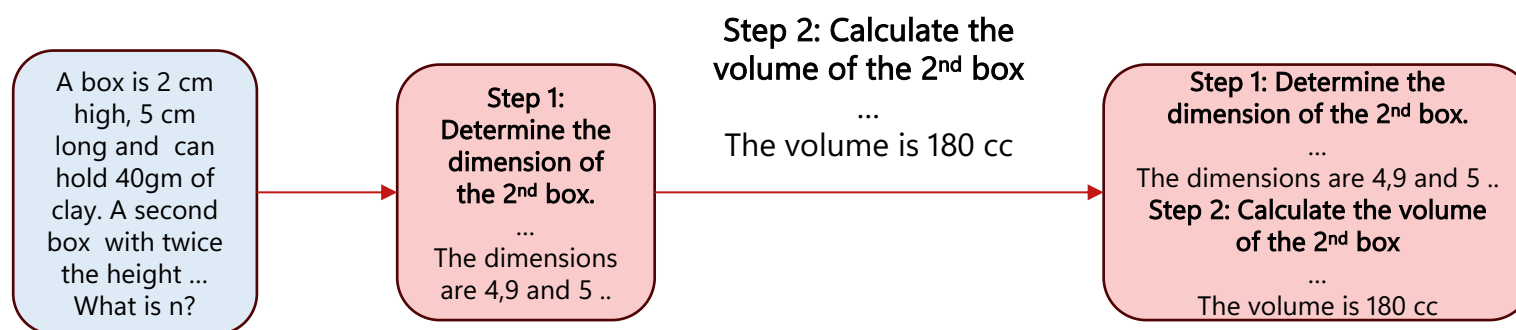
Prompt to generate the backtracking step

Given a partially thought-out solution to a math problem so far which ends by identifying itself to be incorrect and needing to backtrack, the "backtracked" step that the solution is supposed to backtrack to, your job is to continue the existing solution thoughts by backtracking to the part of the solution that corresponds to the "backtracked step".



Generating the tree – Markov Chain Tree Search

- Each node S_t represents a partial solution till that point
- The edges, representing the actions a_t in MCTS - a step of the solution

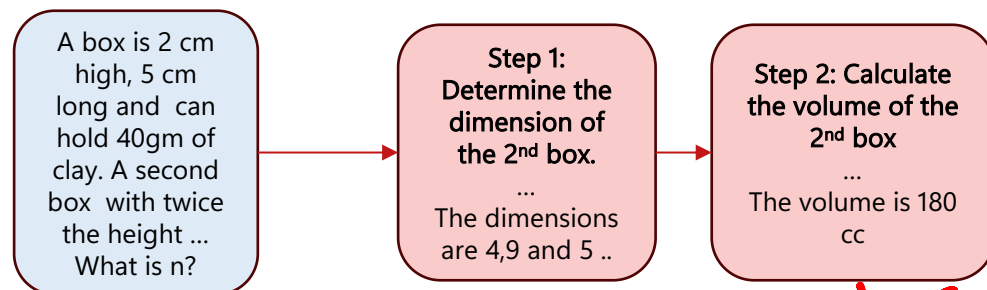


Too clumsy !!



Generating the tree – Markov Chain Tree Search

- Each node represents a partial solution till that point
- The edges correspond to an action - a step



- So*
- Partial Solution so far*
- Which node should I expand next?
 - Which node is most likely to reach the correct solution?
 - We need a way to evaluate the nodes.
- Step = (S_t, a_t)*



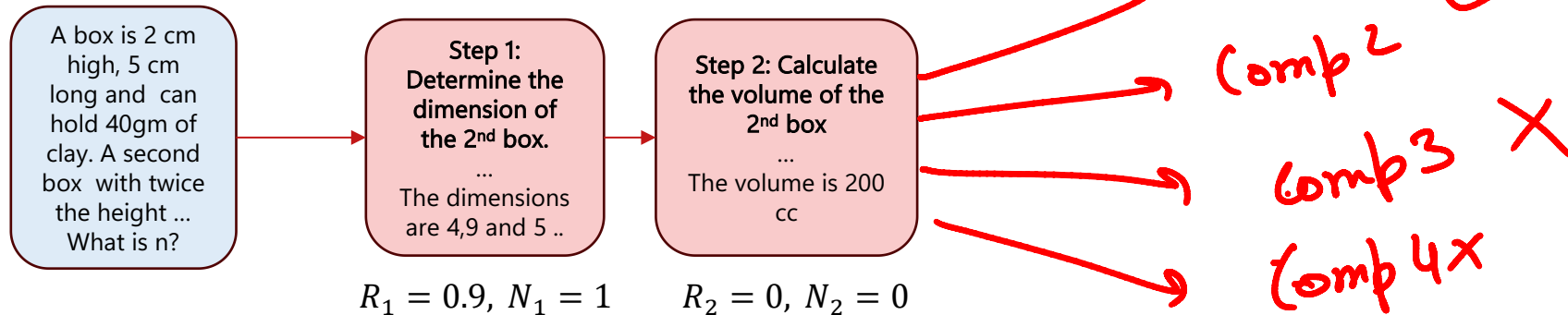
Reward at a node

- Given a node S_t representing a partial solution

- Sample multiple completions $\Pi_{LM,j}(S_t)$ of the partial solution.
- Compare the answer against a ground-truth G using a verifier Ver
- The reward of the node

$$R(S_t) = \frac{1}{N} \sum_{j=1}^N Ver(\Pi_{LM,j}(S_t), G)$$

$$R_2 = \frac{2}{4} = 0.5$$



Q-value of an action

- Given the state-action pair (S_{t-1}, a)
- The next state after taking a at S_{t-1} is S_t
- A weighted average
 - Reward of the next state
 - Q-value of taking each action at the next state
 - State-action pairs that have been traversed more contribute more

$$Q(S_{t-1}, a) = \frac{\sum_{a'} Q(S_t, a') N(S_t, a') + R(S_t)}{\sum_{a'} N(S_t, a') + 1}$$

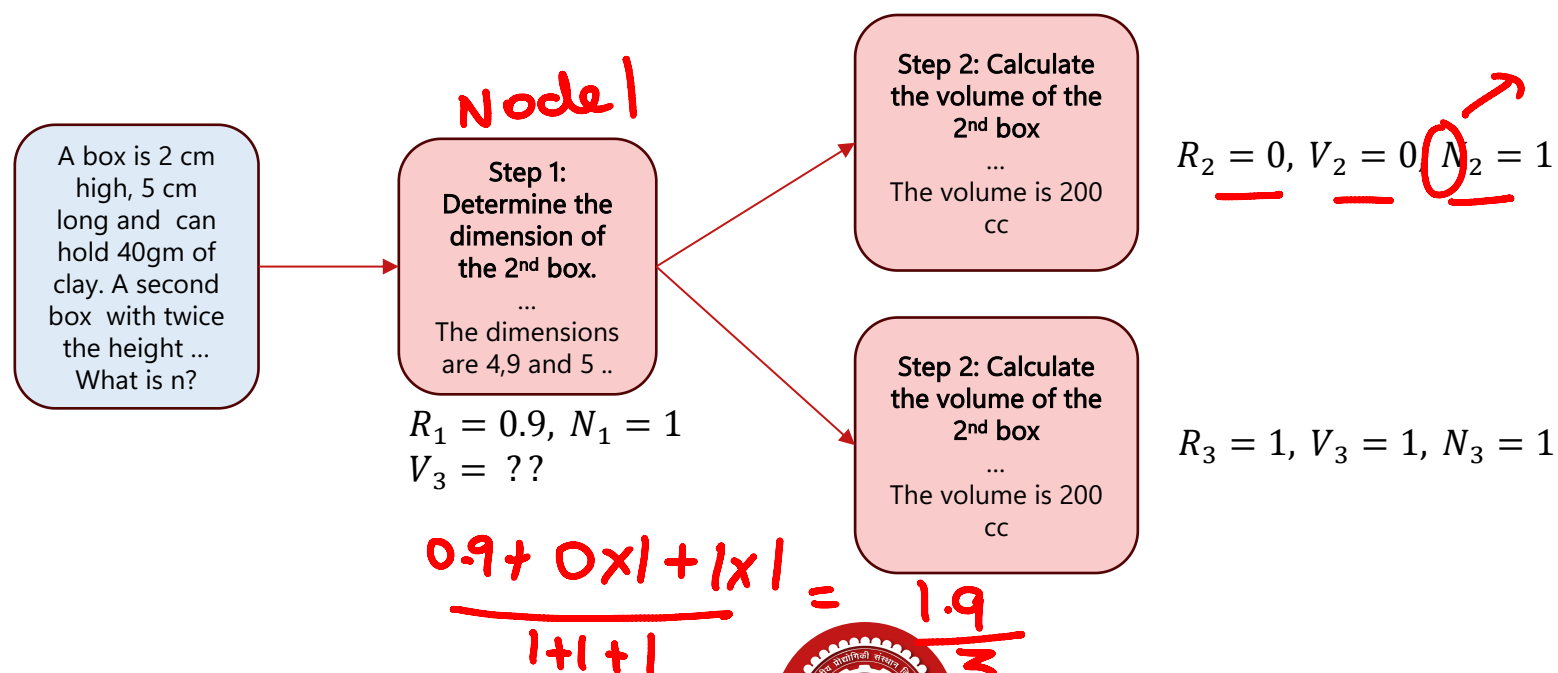


Q-value for stepwise generation from LLMs

- A weighted average
 - Its own reward
 - Value of its children

$$V(S_t) = \frac{\sum_{S \in \mathcal{N}(S_t)} V(S) N(S) + R(S_t)}{\sum_{S \in \mathcal{N}(S_t)} N(S) + 1}$$

Handwritten notes:
- $\mathcal{N}(S_t)$: children of S_t
- $R(S_t)$: reward of node itself
- $N(S)$: no. of times the state S has been selected



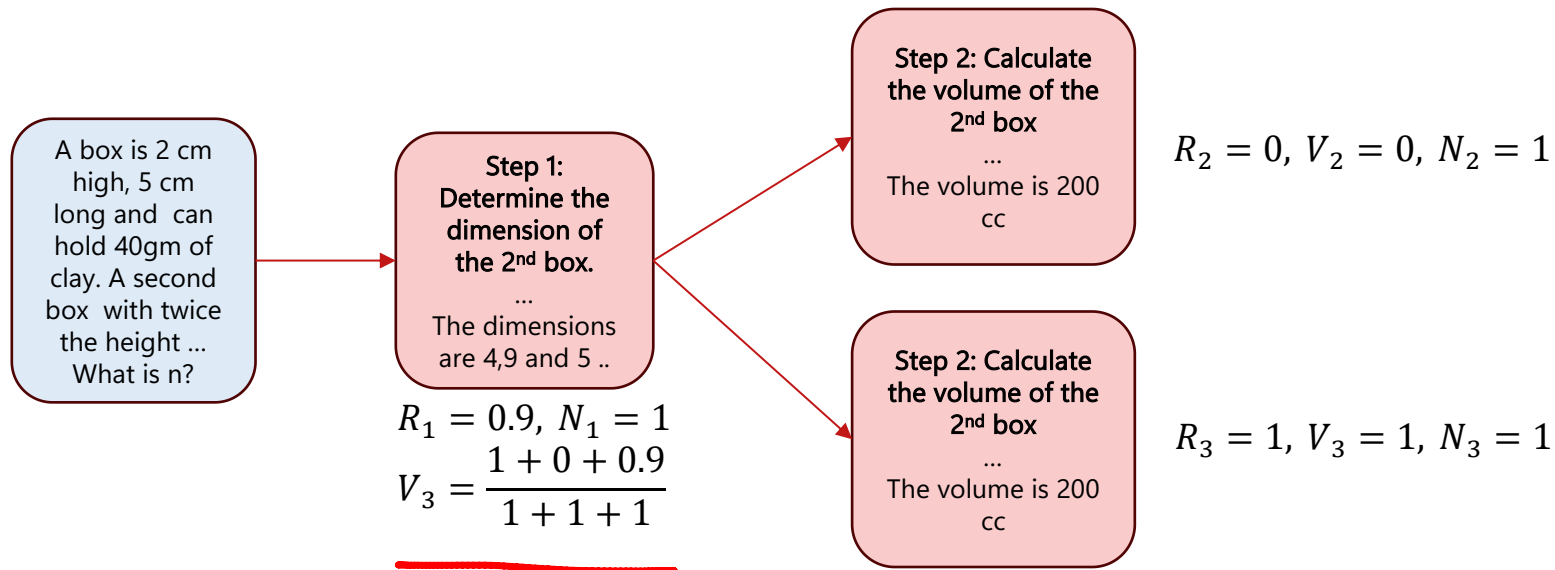
Handwritten note:
How many times this node has been seen



Value at a node

- A weighted average
 - Its own reward
 - Value of its children

$$V(S_t) = \frac{\sum_{S \in \mathcal{N}(S_t)} V(S)N(S) + R(S_t)}{\sum_{S \in \mathcal{N}(S_t)} N(S) + 1}$$



The 4 steps of MCTS

- Selection
 - Which node should I select for expansion?

- Expansion

- How do I sample the next step?

→ Sample the next step from a selected node?

- Evaluation

- How do I evaluate the node?

→ Compute the reward.

- Backpropagation

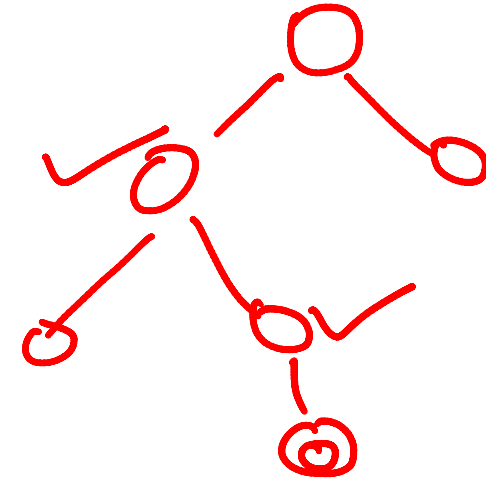
- How do I propagate the reward upwards?

→ Computing the value function
Starting from leaves



Selection

- Exploitation only
 - Select the node that has the highest value function $V(S_{t+1})$
- Exploration only
 - Select the node that has not been well-explored



$$\left\{ \frac{\sqrt{N(S_t)}}{1 + N(S_{t+1})} \right\} \quad \frac{1}{N(S_{t+1})}$$

- Exploration vs Exploitation

$$S_{t+1}^* = \underset{S_{t+1}=S_t \rightarrow a_i}{\operatorname{argmax}} \left[V(S_{t+1}) + c_{\text{puct}} \cdot \Pi_{LM}(a_i|S_t) \cdot \frac{\sqrt{N(S_t)}}{1 + N(S_{t+1})} \right]$$

Predictor+Upper Confidence bounds applied to Trees (PUCT, Silver et al. (2016))

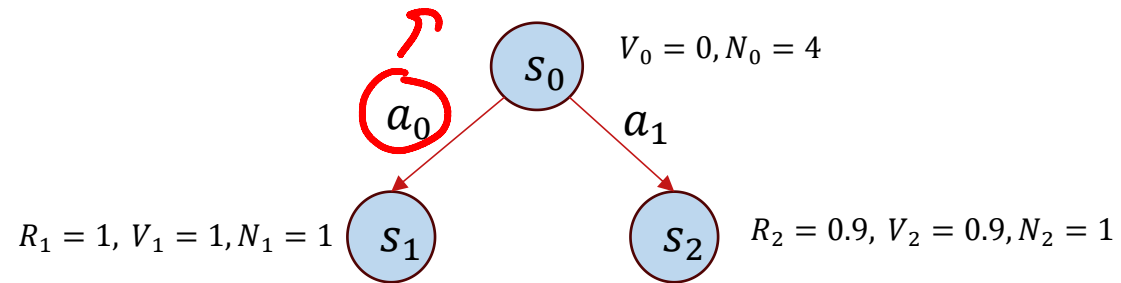


Expansion, Evaluation and Backpropagation

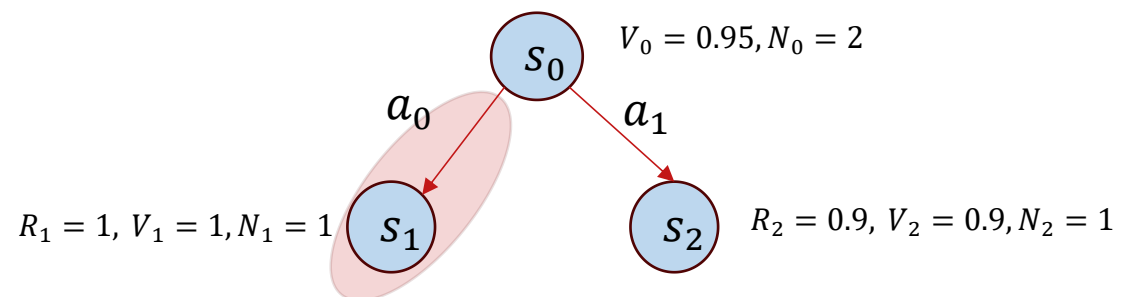
- The selected node corresponds to a partial solution
- Sample k next steps given the partial solution → Expansion
- Compute the reward of each partial solution with the next step added. → Evaluation
- Update the value at each node from the reward and value of its children → Backtracking



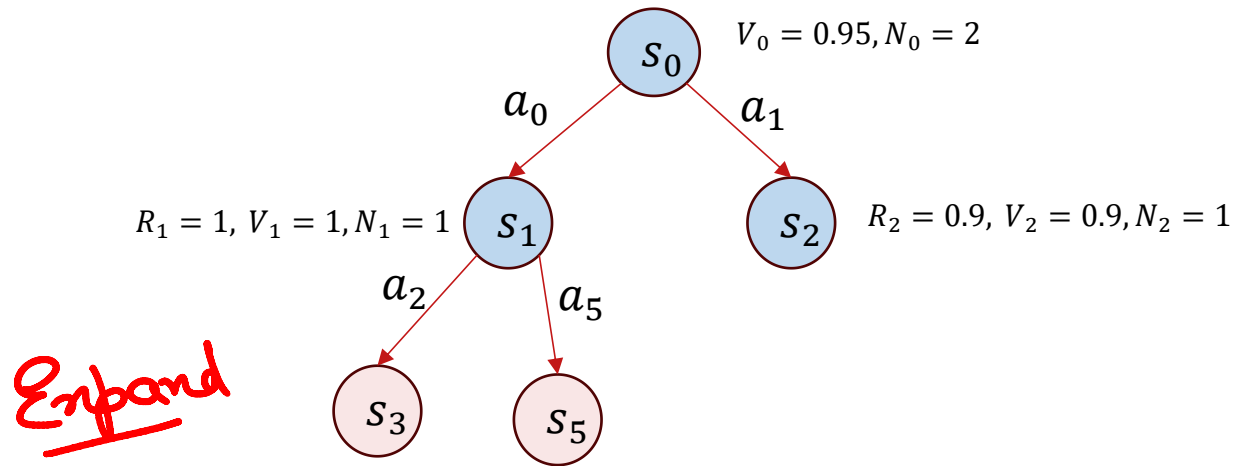
An illustration *one step of the solution*



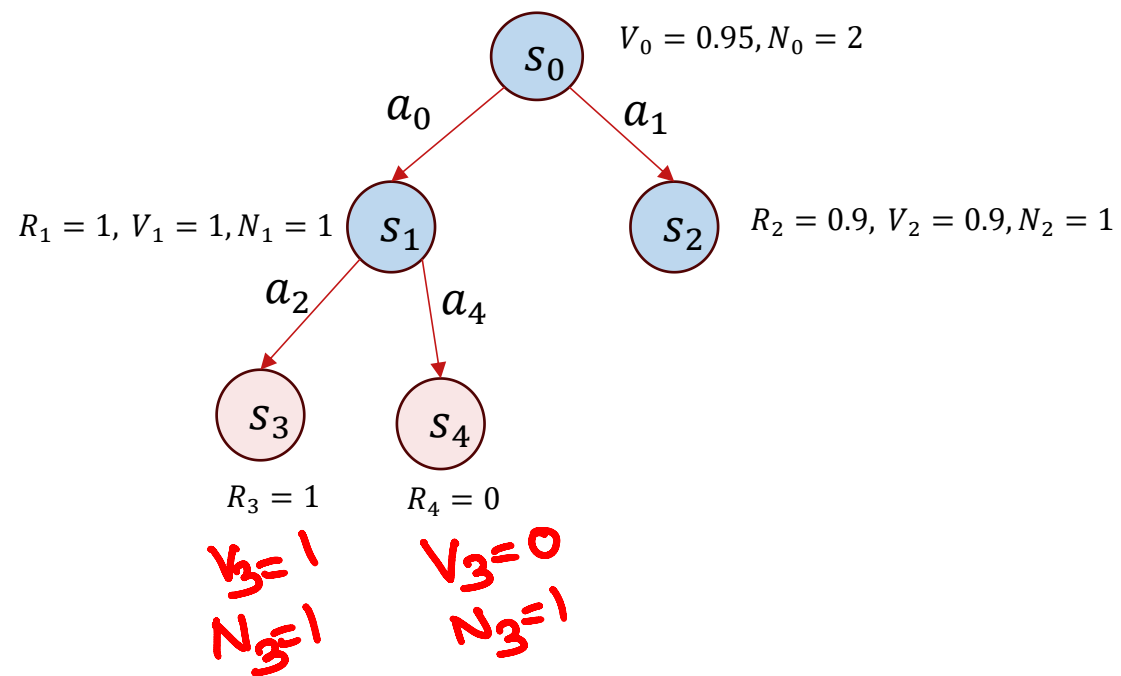
Selection



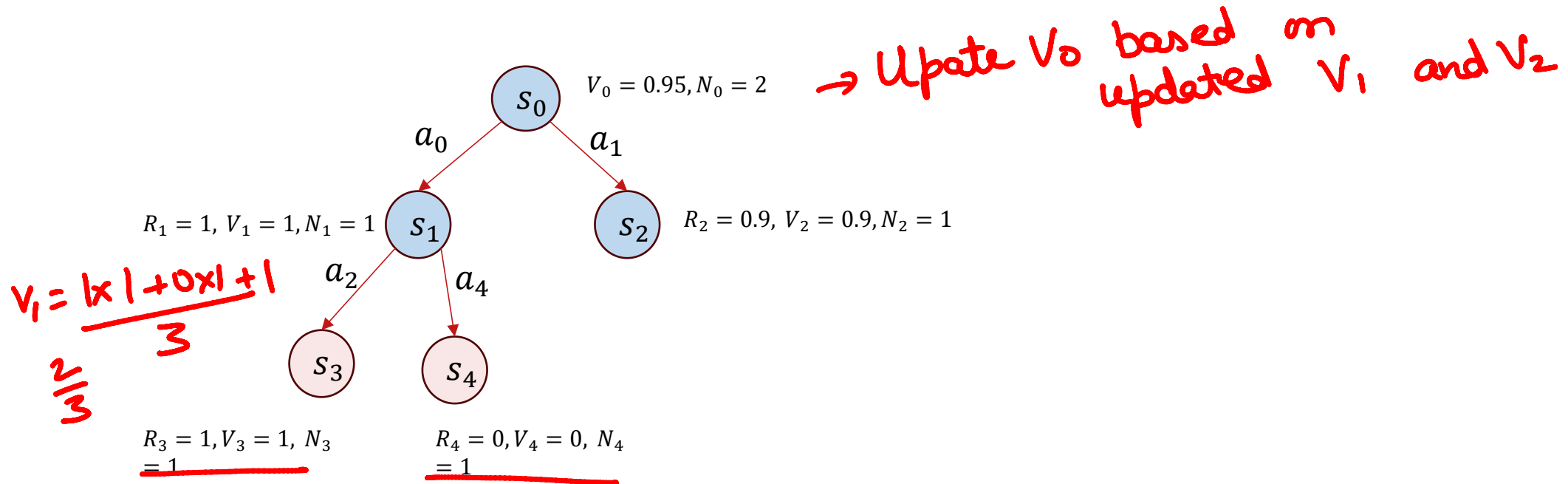
Expansion



Evaluation

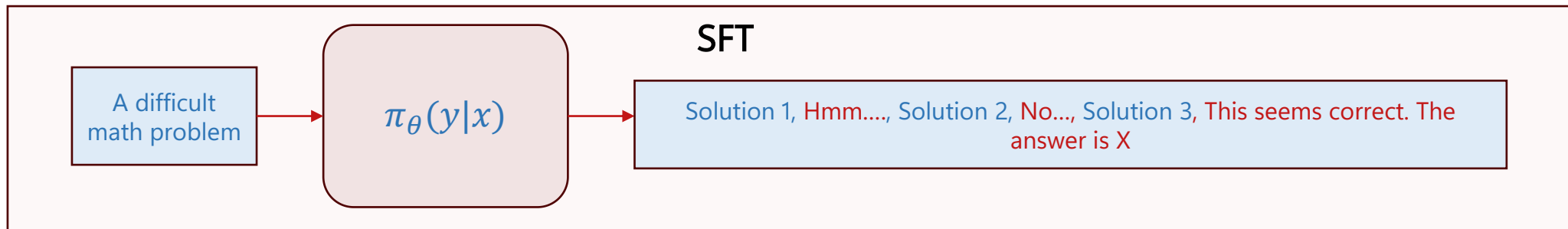


Backpropagation



Training

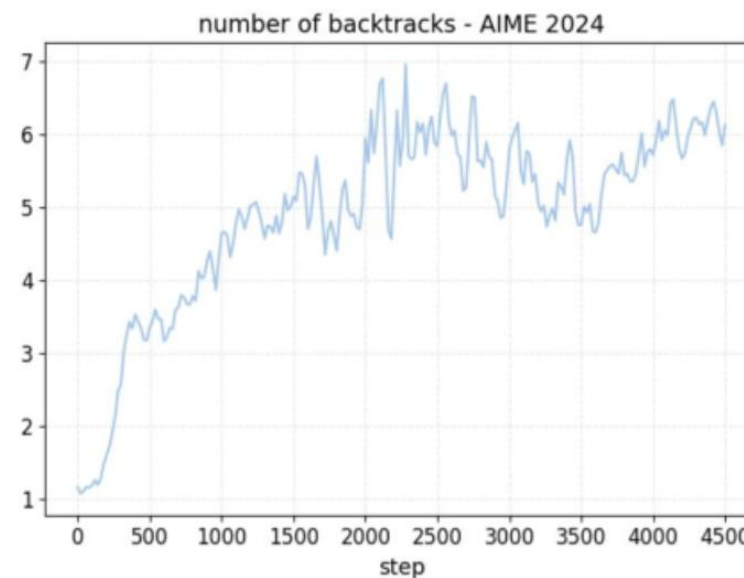
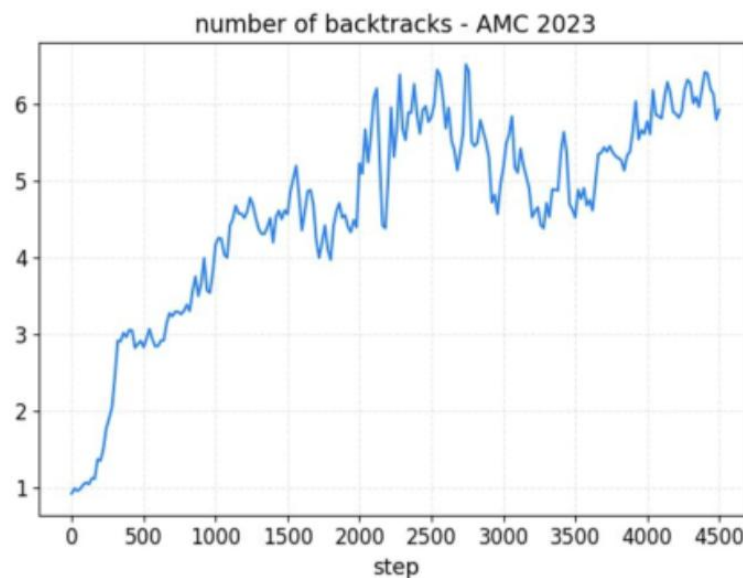
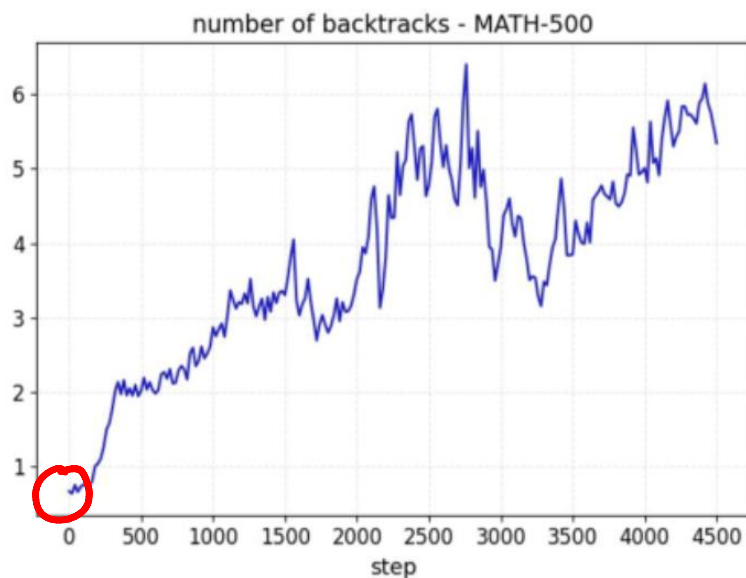
- The SFT model is trained on linearized traces
- This teaches the model how to reason



- This is followed by reinforcement learning – GRPO + RLVR



Does backtracking increase with RL training?



ASTRO: Teaching Language Models to Reason by Reflecting and Backtracking In-Context



Advances in LLMs



Gaurav Pandey

Direct vs backtracked solutions

Non-linearization - Pick the correct path

Checkpoint	MATH-500	AMC 2023		AIME 2024	
	pass@1	pass@1	maj@8	pass@1	maj@8
Llama-3.1-70B-Direct-SFT	<u>65.8</u>	<u>45.2</u>	58.0	<u>16.7</u>	23.3
Llama-3.1-70B-ASTRO-SFT	<u>69.6</u>	51.9	<u>63.0</u>	<u>13.3</u>	16.7
Llama-3.1-70B-Direct-RL	79.8	60.5	67.8	27.1	30.3
Llama-3.1-70B-ASTRO-RL	81.8	64.4	68.8	30.0	32.0

ASTRO: Teaching Language Models to Reason by Reflecting and Backtracking In-Context



References & Further Reading

- Chain-of-Thought Prompting Elicits Reasoning in LLMs (2022) — Prompt-only emergence of multi-step solutions.
- STaR: Bootstrapping Reasoning With Rationales (2022) — Self-generate explanations → filter → SFT.
- Thinking LLMs: Thought Preference Optimization (TPO) (2024) — Optimize preferences over thoughts, not just finals.
- ✓ • DeepSeek-R1: Incentivizing Reasoning via RL (2025) — GRPO + verifiers; emergence of planning/backtracking.
- ✓ • Cognitive Behaviors that Enable Self-Improving Reasoners (2025) — behavior presence predicts RL self-improvement
- ASTRO: Teaching Language Models to Reason by Reflecting and Backtracking In-Context (2025) — incorporating reasoning patterns by MCTS

